

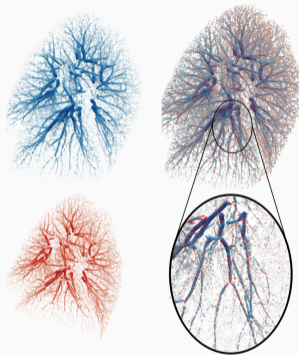
# The geometric software stack: past, present, future

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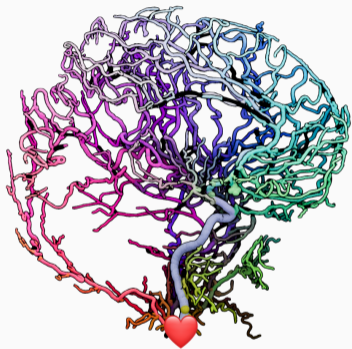
Jean Feydy  
HeKA team, Inria Paris  
Inserm, Université Paris-Cité

28th of October, 2024  
SIGMA 2024  
CIRM, Marseille

## Recent works



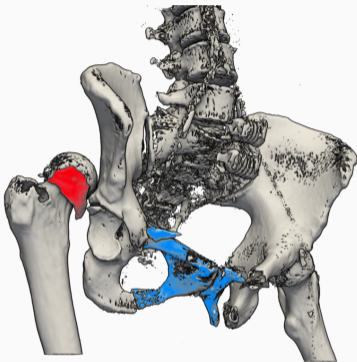
Lung **registration**.



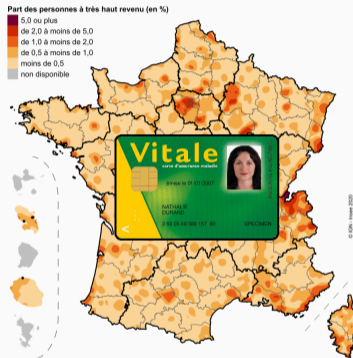
Interventional **radiology**.

⇒ **Accessible** to you guys, but **barely anyone else**.

# Recent works



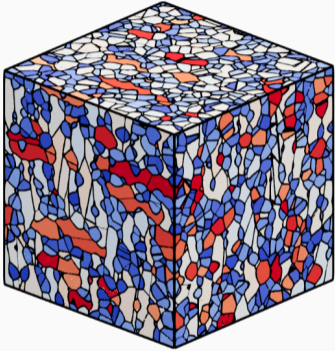
Orthopedic **surgery**.



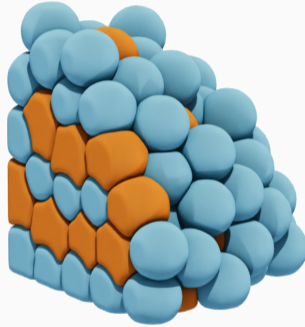
**Public health**.

⇒ **Accessible** to you guys, but **barely anyone else**.

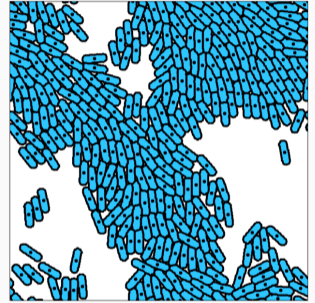
## Recent works



**Metallurgy.**



Swarms of incompressible **cells**.



⇒ **Accessible** to you guys, but **barely anyone else**.



# HeKA : a translational research team for public health

Hospitals

Inria      Inserm

Universities



# Geometric data analysts are in a delicate position

Our constraints:

1. Differential geometry is **not** part of the **mainstream curriculum**  
⇒ High **entry cost** for students and users.
2. **Credibility**  $\Leftrightarrow$  **Performance** and high-resolution figures  
⇒ Constant work to **keep up** with new technology.
3. We are already **very busy**  
⇒ Our **career incentives** do **not** reward long-term software **maintenance**.

## Today's talk – some practical answers to three pressing questions

1. Which **language** and **libraries** should I use?
2. Is my code still going to run in **2030**?
3. How do I get **rewarded** for all of that extra work?

## Which language should I use?

The **C++ era** (2000-2015):

- High-performance C++ was **necessary** to handle **3D data**.
- **Monolithic** code-bases with a lot of **inertia**, cryptic to scientists.
- The Visualization ToolKit, the Computational Geometry Algorithms Library...

The **Python era** (since 2015):

- **Modular** and **inter-operable** tools via dictionaries and NumPy arrays.
- **Permissive** open source licences create trust.
- Scikit-learn, Scikit-image, PyVista, Vedo...

## Which language should I use?

Domain-specific languages are fine too:

- **R** is data-centric: native idiom for biologists and medical doctors.
- **Julia** is convenient for numerical analysis.

But **Python** is the **lingua franca** for **gluing** pipelines together:

1. Identify the key **building blocks** in your method.
2. Implement them in the language that suits you best.
3. Write a **Python interface** – now super easy.

⇒ Speak **French, German** or **Hindi** at home... but publish in **English**.

# The KeOps library: efficient support for symbolic matrices, with Joan and Benjamin

**KeOps** – [www.kernel-operations.io](http://www.kernel-operations.io):

- For PyTorch, NumPy, Matlab and R, on **CPU and GPU**.
- **Automatic differentiation**.
- Just-in-time **compilation** of **optimized** C++ schemes, triggered for every new **reduction**: sum, min, etc.

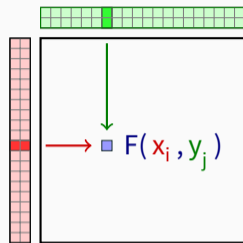
If the formula “F” is simple ( $\leq 100$  arithmetic operations):

“100k  $\times$  100k” computation  $\rightarrow$  10ms – 100ms,

“1M  $\times$  1M” computation  $\rightarrow$  1s – 10s.

Hardware ceiling of  $10^{12}$  operations/s.

$\times 10$  to  $\times 100$  **speed-up** vs standard GPU implementations  
for a wide range of problems.



**Symbolic matrix**

Formula + data

- Distances  $d(x_i, y_j)$ .
- Kernel  $k(x_i, y_j)$ .
- Numerous transforms.

## Yet another python compiler?

Many impressive tools out there (Numba, Triton, Halide, Taichi...):

- Focus on **generality** (software + hardware).
- Increasingly easy to use via e.g. PyTorch 2.0.

KeOps fills a **scientific niche** (like FFT libraries):

- Focus on a **single major bottleneck**: geometric interactions.
- **Agnostic** with respect to Euclidean / non-Euclidean formulas.
- Fully compatible with PyTorch, NumPy, R.
- Can actually be **used by mathematicians** (**700k+** downloads).

KeOps is a **bridge** between geometers (with a maths background)  
and compiler experts (with a CS background).

## Which libraries should I use?

Exciting libraries get **killed** all the time :-)

**Theano** (2008-2017):

- **Pioneering** deep learning library: Python + Autodiff + GPU.
- Created and maintained in Montreal (MILA).
- Development stopped when **PyTorch** became available.

**Taichi** (2017-2023?):

- **Awesome** Python dialect for 3D shape processing and graphics, 25k GitHub stars.
- **PhD thesis** of Yuanming Hu at MIT, now **CEO** of Meshy.
- Active development stopped in the summer of 2023.



## Tip #1: look at the developers' long term incentives

**PyTorch** (Meta) – sending all the **right signals**:

- Business strategy on AI is to make it an **open source commodity**.
- **Transparent governance structure**, PyTorch foundation.
- **Extensive** internal documentation.

**JAX and TensorFlow** (Google) – several **red flags**:

- Business strategy on AI is to protect the **Google search monopoly** and **GCP**.
- **Opaque** governance structure, `killedbygoogle.com`.
- **Minimal** internal documentation.

## Tip #2: Implement a future-proof interface

**Insulate users** from deprecations:

- Numpy arrays.
- Human-readable files.

**User-centric** design:

- Principle of **least surprise**.
- Write **tutorials** – a feature that is not documented **does not exist**.
- Plain, descriptive names:

Kernel → **covariance**

Splines → **deformation**(covariance="thin plate spline")

**LDDMM** → deformation(covariance="gaussian", scale=2, **n\_steps=10**)

## Problem: software rots

Some personal nightmares:

- CMake, **Boost**...
- Nvidia **actively deprecates** “old” GPUs.
- `torch.solve(A, B) = B-1A → A-1B`.

Without **constant gardening**,  
software breaks after 3-5 years.



*Some of my old GitHub repositories.*

# Research you're proud of should be in a library

#1 – Include your model in a **pre-existing** library:

- **Outsource maintenance**, gain visibility.
- Permissive licenses are key: MIT, BSD...

#2 – Develop and maintain **your own** library:

- Be realistic: focus on your **core expertise**.
- Bet on **interoperability** with other packages.
- Freedom for you, minimize risk for users.

⇒ Agree on a **consistent interface** with the community and **keep your word**.



*A professional storage facility.*

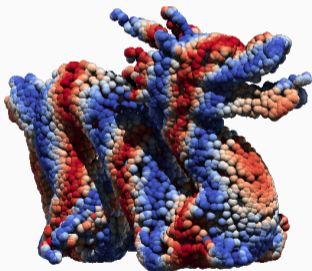
# GeomLoss: scaling up optimal transport to anatomical data

Progresses of the last decade add up to a  $\times 100$  -  $\times 1000$  acceleration:

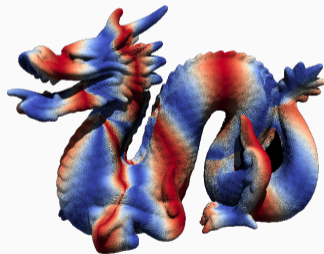
Sinkhorn GPU  $\xrightarrow{\times 10}$  + KeOps  $\xrightarrow{\times 10}$  + Annealing  $\xrightarrow{\times 10}$  + Multi-scale

With a precision of 1%, on a modern gaming GPU:

```
pip install  
geomloss  
+  
gaming GPU  
(1 000 €)
```



10k points in 30-50ms



100k points in 100-200ms

## GeomLoss: going forward

Current landscape in computational optimal transport:

- **Python Optimal Transport (POT)**: tons of tutorials, but slow solvers from 2015.
- Mérigot, Lévy, De Goes: super-fast OT solvers for **physics**.
- Schmitzer, GeomLoss: super-fast OT solvers for **geometric data**.
- Massive **waste of time for newcomers** in the field.

How to solve the issue:

- Agree on a **common interface**.
- Include GeomLoss and others as **optional backends** in POT.
- **Automated benchmark** website to highlight “solved” and “open” problems.

⇒ Put egos aside, move forward as a community.

→ Only possible because we are not judged by our h-index.

# But Jean... I'm just a mathematician!

Writing good code is easy now!

Use **professional tools**:

- Black and Ruff **beautify** your code.
- Pytest and Hypothesis **find bugs**.
- Copilot **writes documentation**.
- Sphinx creates a **clean website**.
- GitHub actions **deploy automagically**.

Check out **[scientific-python.org](https://scientific-python.org)**.



*Invest in **power tools**.*

## But Jean... I'm just a mathematician!

### Why should I bother?

- If you don't code your method first, **no one will**.
- Get to meet a wide range of **exciting users**.
- Open up **career paths** for students.

### Publish or perish?

- French open source software awards from the Ministry of research.
- At INRIA, **clear incentives** for software development.
- Career paths for **research engineers** in academia?



# From Deformetrica to scikit-shapes (with an ‘s’)

## scikit-shapes:

- Follows the tips above!
- Named after **scikit-image**: a reference library for classical image processing.
- Targets shape data analysis.
- **Abstracts** multiscaling and feature extraction.
- **Foundations** are now solid (Louis Pujol).
- Funded by INRIA and Prairie.

## Next steps:

- GPMM, elastic metrics, functional maps.
- **Research** on robustness and modularity.
- Ready for JupyterLite + WebGPU ?

Scikit-Shapes 0.1 documentation

### Gallery of examples

The examples below shows functionalities of scikit-shapes.

#### Data

The data classes are designed to store geometric data and associated features for shape analysis.

**PolyData conversion**  
from and to PyVista or Vedo

**The PolyData class:**  
point cloud, wireframe and triangle meshes

#### Multiscaling

Representing data at various scale is a core feature of scikit-shapes: in addition to data compression, we provide tools for preserving features across scales.

**Multiscaling (triangle mesh)**

**Multiscaling and landmarks**

**Multiscaling and signal propagation**

#### Registration

[scikit-shapes.github.io](https://github.com/scikit-shapes/scikit-shapes)

Check it out in 2025!

# Our community is judged by its software output



*The C++ tower of Babel.*



*The Python market of ideas.*

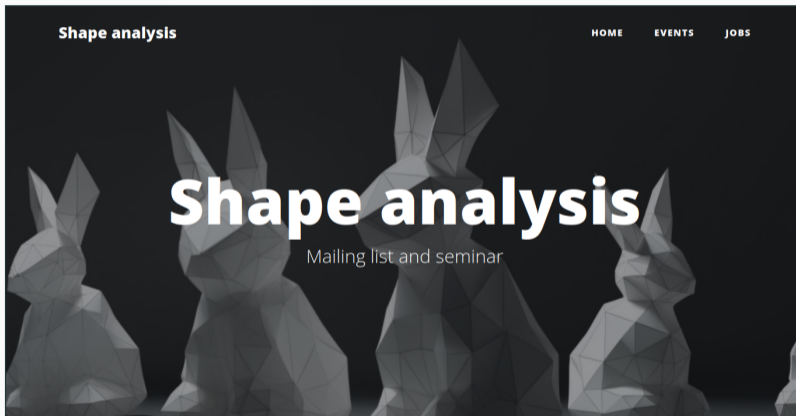
Major challenge: beyond goodwill, create **sustainable open business models**.

Are **universities** hostile environments? Kitware (VTK), Tutte Institute (UMAP), INRIA...

## Documentation and tutorials are available online



[shape-analysis.github.io](https://shape-analysis.github.io)



Monthly seminar, videos on YouTube.

## References

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