The geometric software stack: past, present, future

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10th of February, 2025 Infinite-dimensional Geometry: Theory and Applications Erwin Schrödinger Institute, Vienna **Recent works**

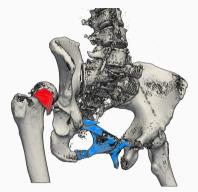


Lung registration.

Interventional radiology.

⇒ Accessible to you guys, but barely anyone else.

Recent works



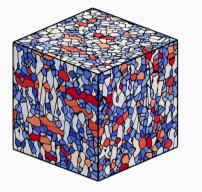


Orthopedic surgery.

Public health.

 \implies Accessible to you guys, but barely anyone else.

Recent works







Metallurgy.

Swarms of incompressible **cells**.

 \implies Accessible to you guys, but barely anyone else.

HeKA : a translational research team for public health

Hospitals Inria Inserm

Universities



Our constraints:

- 1. Differential geometry is **not** part of the **mainstream curriculum**
 - \implies High **entry cost** for students and users.

- 2. **Credibility** \iff **Performance** and high-resolution figures
 - \implies Constant work to **keep up** with new technology.

- 3. We are already very busy
 - \implies Our career incentives do not reward long-term software maintenance.

- 1. Which language and libraries should I use?
- 2. Is my code still going to run in 2030?
- 3. How do I get **rewarded** for all of that extra work?

The **C++ era** (2000-2015):

- High-performance C++ was **necessary** to handle **3D data**.
- Monolithic code-bases with a lot of inertia, cryptic to scientists.
- The Visualization ToolKit, the Computational Geometry Algorithms Library...

The **Python era** (since 2015):

- Modular and inter-operable tools via dictionaries and NumPy arrays.
- Permissive open source licences create trust.
- Scikit-learn, Scikit-image, PyVista, Vedo...

Domain-specific languages are fine too:

- R is data-centric: native idiom for biologists and medical doctors.
- Julia is convenient for numerical analysis.

But **Python** is the **lingua franca** for **gluing** pipelines together:

- 1. Identify the key **building blocks** in your method.
- 2. Implement them in the language that suits you best.
- 3. Write a **Python interface** now super easy.

⇒ Speak **French**, **German** or **Hindi** at home… but publish in **English**.

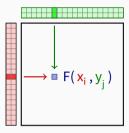
The KeOps library: efficient support for symbolic matrices, with Joan and Benjamin

KeOps -www.kernel-operations.io:

- For PyTorch, NumPy, Matlab and R, on **CPU and GPU**.
- Automatic differentiation.
- Just-in-time **compilation** of **optimized** C++ schemes, triggered for every new **reduction**: sum, min, etc.

If the formula "F" is simple (\leq 100 arithmetic operations): "100k × 100k" computation \rightarrow 10ms – 100ms, "1M × 1M" computation \rightarrow 1s – 10s.

Hardware ceiling of 10¹² operations/s. ×10 to ×100 speed-up vs standard GPU implementations for a wide range of problems.



Symbolic matrix Formula + data

- Distances d(x_i,y_i).
- Kernel k(x_i,y_i).
- Numerous
 transforms.

Many impressive tools out there (Numba, Triton, Halide, Taichi...):

- Focus on **generality** (software + hardware).
- Increasingly easy to use via e.g. PyTorch 2.0.

KeOps fills a **scientific niche** (like FFT libraries):

- Focus on a single major bottleneck: geometric interactions.
- Agnostic with respect to Euclidean / non-Euclidean formulas.
- Fully compatible with PyTorch, NumPy, R.
- Can actually be used by mathematicians (700k+ downloads).

KeOps is a **bridge** between geometers (with a maths background) and compiler experts (with a CS background). Exciting libraries get killed all the time :-(

Theano (2008-2017):

- **Pioneering** deep learning library: Python + Autodiff + GPU.
- Created and maintained in Montreal (MILA).
- Development stopped when **PyTorch** became available.

Taichi (2017-2023?):

- Awesome Python dialect for 3D shape processing and graphics, 25k GitHub stars.
- PhD thesis of Yuanming Hu at MIT, now CEO of Meshy.
- Active development stopped in the summer of 2023.

PyTorch (Meta) – sending all the **right signals**:

- Business strategy on AI is to make it an **open source commodity**.
- Transparent governance structure, PyTorch foundation.
- Extensive internal documentation.

JAX and TensorFlow (Google) – several red flags:

- Business strategy on AI is to protect the Google search monopoly and GCP.
- **Opaque** governance structure, killedbygoogle.com.
- Minimal internal documentation.

Tip #2: Implement a future-proof interface

Insulate users from deprecations:

- Numpy arrays.
- Human-readable files.

User-centric design:

- Principle of least surprise.
- Write tutorials a feature that is not documented does not exist.
- Plain, descriptive names:
- Kernel \longrightarrow covariance
- Splines \rightarrow deformation(covariance="thin plate spline")
- LDDMM \rightarrow deformation(covariance="gaussian", scale=2, n_steps=10)

Some personal nightmares:

- CMake, Boost...
- Nvidia actively deprecates "old" GPUs.
- torch.solve(A, B) $= B^{-1}A \rightarrow A^{-1}B$.

Without **constant gardening**, software breaks after 3-5 years.



Some of my old GitHub repositories.

Research you're proud of should be in a library

#1 – Include your model in a **pre-existing** library:

- Outsource maintenance, gain visibility.
- Permissive licenses are key: MIT, BSD...
- **#2** Develop and maintain **your own** library:
 - Be realistic: focus on your **core expertise**.
 - Bet on interoperability with other packages.
 - Freedom for you, minimize risk for users.

⇒ Agree on a consistent interface with the community and keep your word.



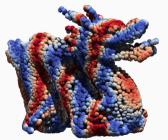
A professional storage facility.

GeomLoss: scaling up optimal transport to anatomical data

Progresses of the last decade add up to a $\times 100 - \times 1000$ acceleration: Sinkhorn GPU $\xrightarrow{\times 10}$ + KeOps $\xrightarrow{\times 10}$ + Annealing $\xrightarrow{\times 10}$ + Multi-scale

With a precision of 1%, on a modern gaming GPU:

pip install geomloss + gaming GPU (1000€)



10k points in 30-50ms



100k points in 100-200ms

Current landscape in computational optimal transport:

- Python Optimal Transport (POT): tons of tutorials, but slow solvers from 2015.
- Mérigot, Lévy, De Goes: super-fast OT solvers for **physics**.
- Schmitzer, GeomLoss: super-fast OT solvers for geometric data.
- Massive waste of time for newcomers in the field.

How to solve the issue:

- Agree on a **common interface**.
- Include GeomLoss and others as **optional backends** in POT.
- Automated benchmark website to highlight "solved" and "open" problems.
- \implies Put egos aside, move forward as a community.
- $\longrightarrow~$ Only possible because we are not judged by our h-index.

Writing good code is easy now! Use **professional tools**:

- Black and Ruff **beautify** your code.
- Pytest and Hypothesis find bugs.
- Copilot writes documentation.
- Sphinx creates a **clean website**.
- GitHub actions **deploy automagically**.

Check out scientific-python.org.



Invest in **power** tools.

Why should I bother?

- If you don't code your method first, no one will.
- Get to meet a wide range of **exciting users**.
- Open up career paths for students.

Publish or perish?

- French open source software awards from the Ministry of research.
- At INRIA, clear incentives for software development.
- Career paths for research engineers in academia?

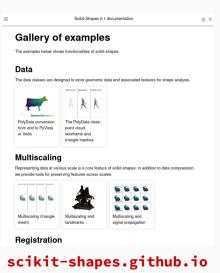
From Deformetrica to scikit-shapes (with an 's')

scikit-shapes:

- Follows the tips above!
- Named after scikit-image: a reference library for classical image processing.
- Targets shape data analysis.
- Abstracts multiscaling and feature extraction.
- Foundations are now solid (Louis Pujol).
- Funded by INRIA and Prairie.

Next steps:

- GPMM, elastic metrics, functional maps.
- **Research** on robustness and modularity.
- Ready for JupyterLite + WebGPU ?



Check it out in a few months! 21

Our community is judged by its software output



The C++ tower of Babel.



The Python market of ideas.

Major challenge: beyond goodwill, create **sustainable open business models**. Are **universities** hostile environments? Kitware (VTK), Tutte Institute (UMAP), INRIA...

Documentation and tutorials are available online





Monthly seminar, videos on YouTube.

References

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